

Time series modelling with the “Prophet” [2017]

Forecasting at Scale

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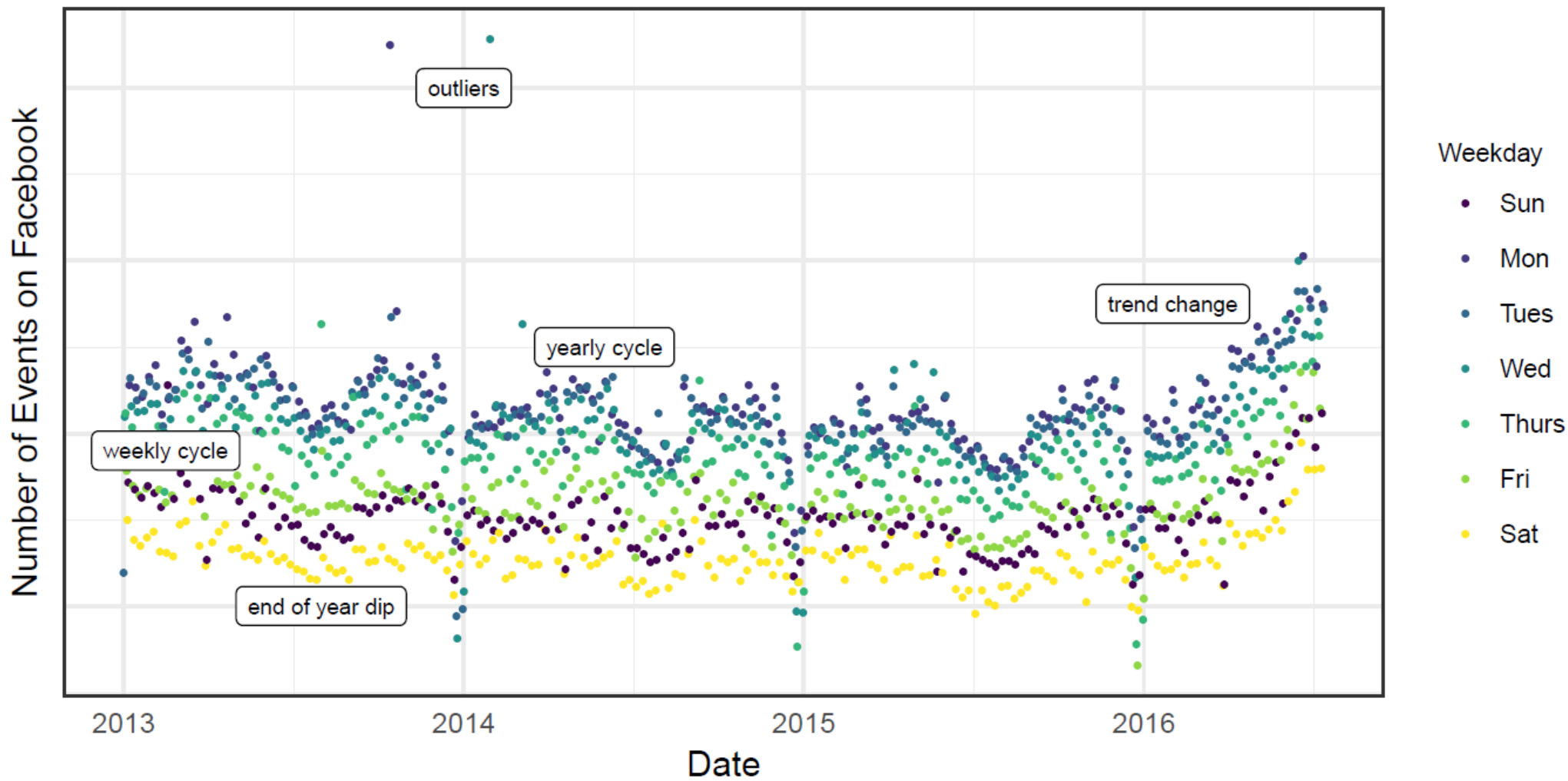
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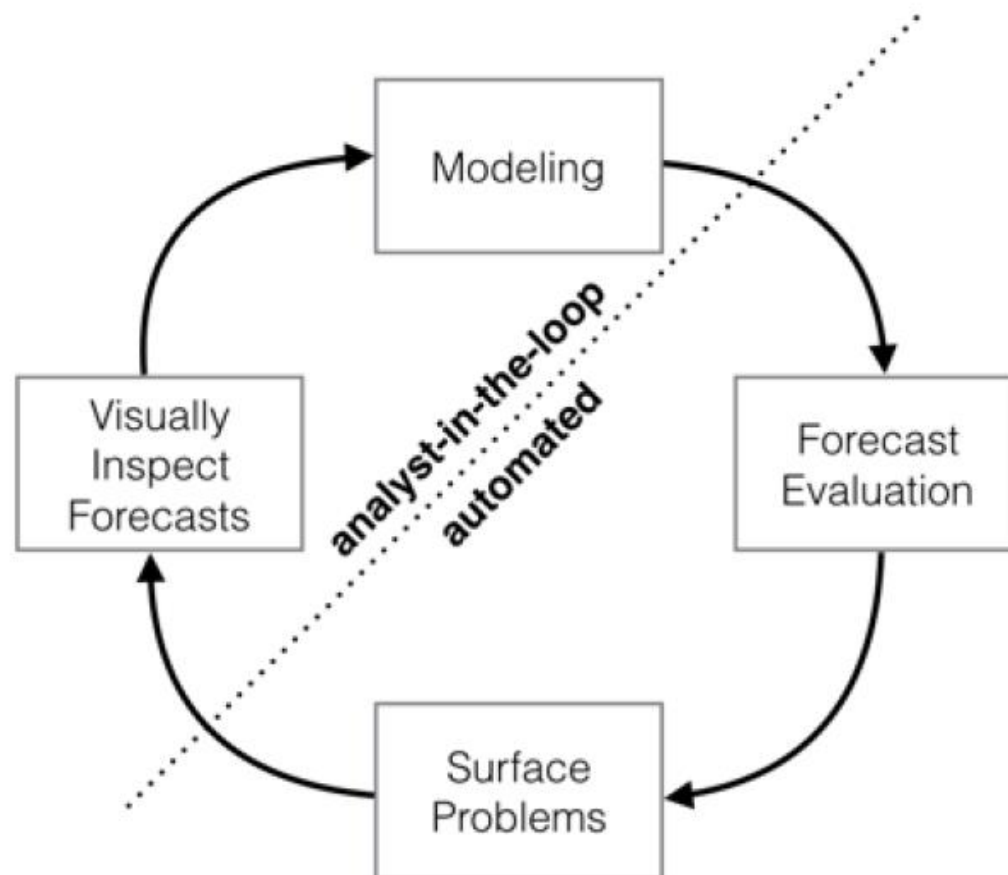
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Input to the model

- ‘Past’ training samples $\{t_k, y_k\}$
- Information about change point locations $\{s_j\}_1^S$ - optional
- Information about seasonality $P = 7$ (weekly), $P = 365.25$ (yearly) - optional
- Information about special types of days/events (e.g holidays) - optional.
- For any type of special day i , there is the set D_i of days of this type. So, for any time sample (past or future) we have a vector

$$Z(t) = [1_{t \in D_1}, \dots, 1_{t \in D_L}].$$

Model

- Additive model

$$y(t) = \underbrace{g(t)}_{\text{trend}} + \underbrace{s(t)}_{\text{seasonality}} + \underbrace{h(t)}_{\text{special events}} + \underbrace{\varepsilon(t)}_{\text{noise}}$$

- Each component has set of parameters that needs to be ‘learnt’ through maximization of likelihood.
- Combination of Bayesian data analysis and constructive approximation.
- Suppose that the model has parameters θ . Bayes’ rule allows to find ‘optimal’ parameters under prior assumptions on $p(\theta)$.

- Posterior density
$$p(\theta|y) = \frac{p(\theta) p(y|\theta)}{p(y)},$$

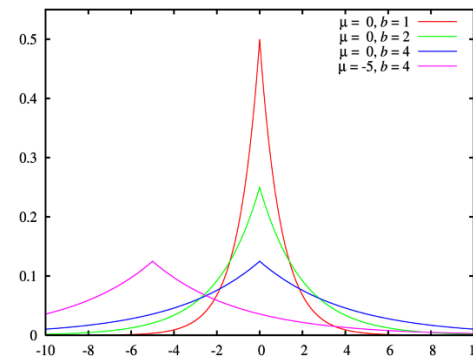
- Unnormalized posterior density $p(\theta|y) \propto p(\theta)p(y|\theta)$
- We can maximize likelihood of posterior.
- The forecast is a distribution, at each t there is a mean with some level of certainty.

Trend model (nonlinear approximation)

- Logistic growth model with fixed capacity

$$\tilde{g}(t) = \frac{C}{1 + e^{-k(t-m)}}, \quad k \text{ growth rate, } m \text{ offset.}$$

- The Prophet model allows capacity & growth to change.
- we model an expected continuous capacity $C(t)$, e.g. a linear function. Could be provided explicitly, e.g. world population estimates.
- Growth allowed to change at times $\{s_j\}_{j=1}^S$, with changes $\{\delta_j\}_{j=1}^S$.
- Prior $\delta_j \sim \text{Laplace}(0, \tau)$, allows negative growth change.



- Rate at time t is modeled as a piecewise constant

$$k + \sum_{j, t \geq s_j} \delta_j = k + \langle a(t), \delta \rangle, \quad a_j(t) = 1_{t \geq s_j}.$$

- The locations $\{s_j\}_{j=1}^S$ can be provided as input or found through automatic selection with a sparse prior such as: one per month.
- To achieve continuity of g , the offset parameter also needs to change at the change points.

- So the trend model is

$$g(t) = \frac{C(t)}{1 + e^{-(k + \langle a(t), \delta \rangle)(t - (m + \langle a(t), \gamma \rangle))}},$$

with

$$\gamma_j = \left(s_j - m - \sum_{l < j} \gamma_l \right) \left(\frac{\delta_j}{k + \sum_{l \leq j} \delta_l} \right)$$

Proof (of continuity of g) Denote $X := k + \sum_{l < j} \delta_l$,

$$Y := s_j - m - \sum_{l < j} \gamma_l$$

For continuity we need $XY \underset{t \rightarrow (s_j)_-}{=} \underbrace{(X + \delta_j)(Y - \gamma_j)}_{t \rightarrow (s_j)_+}$.

$$XY = (X + \delta_j)(Y - \gamma_j) \Leftrightarrow \gamma_j = \frac{Y\delta_j}{X + \delta_j} \Leftrightarrow$$

$$\gamma_j = \left(s_j - m - \sum_{l < j} \gamma_l \right) \left(\frac{\delta_j}{k + \sum_{l \leq j} \delta_l} \right)$$

Seasonality model

- We use a Fourier series approximation

$$s(t) = \sum_{n=1}^N \left(a_n \cos\left(\frac{2\pi nt}{P}\right) + b_n \sin\left(\frac{2\pi nt}{P}\right) \right)$$

- There are $2N$ parameters to learn $\beta = [a_1, b_1, \dots, a_n, b_n]$.
- For yearly the authors chose $N = 10$, for weekly $N = 3$. It provides a low-pass filter
- Smoothing prior $\beta_j \sim N(0, \sigma^2)$.

Special events model

- D_i set of special days of type i . So, we have a vector

$$Z(t) = [1_{t \in D_1}, \dots, 1_{t \in D_L}].$$

- Observe this can be specified for forecasted time points.
- Special events regression $\kappa = \{\kappa\}_{i=1}^L$, prior $\kappa_i \sim N(0, \nu^2)$,

$$h(t) = \langle Z(t), \kappa \rangle.$$

- Sometimes one places a ‘window’ around the special days, making surrounding days also special.

Listing 1: Example Stan code for our complete model.

```
model {  
  // Priors  
  k ~ normal(0, 5);  
  m ~ normal(0, 5);  
  epsilon ~ normal(0, 0.5);  
  delta ~ double_exponential(0, tau);  
  beta ~ normal(0, sigma);  
  
  // Logistic likelihood  
  y ~ normal(C ./ (1 + exp(-(k + A * delta) .* (t - (m + A * gamma)))) +  
            X * beta, epsilon);  
  
  // Linear likelihood  
  y ~ normal((k + A * delta) .* t + (m + A * gamma) + X * beta, sigma);  
}
```